L Number	Hits	Search Text	DB	Time stamp
7	97	(382/153).CCLS.	USPAT; US-PGPUB	2003/07/02 17:24
8	174	(382/152).CCLS.	USPAT; US-PGPUB	2003/07/02 17:24
9	32	((382/152).CCLS.) and robot	USPAT; US-PGPUB	2003/07/02 17:26
10	45	((382/151).CCLS.) and robot	USPAT; US-PGPUB	2003/07/02 17:27
11	7	arimatsu-taro.in.	USPAT; US-PGPUB	2003/07/02 17:29
12	130	watanabe-atsushi.in.	USPAT; US-PGPUB	2003/07/02 17:29
14	7	382/141-154;901/47.ccls. and watanabe-atsushi.in.	USPAT; US-PGPUB	2003/07/02 17:30
15	52	(robot) same (plural$3 or multiple or dual or two or several or many) adj (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj piece or part or model)	USPAT; US-PGPUB	2003/07/02 17:34
16	7	((382/154).CCLS.) and (reference or register$3 or registration or teach$3 or train$3 or learn$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot	USPAT; US-PGPUB	2003/07/02 17:44
18	58	(robot) same (video or camera or CCD or image or visual) same (predetermined or known or specifi$2 or determined) near distance	USPAT; US-PGPUB	2003/07/02 17:45
20	27	robot same (2-D or two-D or two-dimension$2 or "2"-dimension$2 or bi-dimensional or (two or "2") adj dimension$2) with distance	USPAT; US-PGPUB	2003/07/02 17:47
21	15	robot same (reference or register$3 or registration or teach$3 or train$3 or learn$3) same (video or camera or CCD or image or visual) same (predetermined or known or specifi$2 or determined) near distance	USPAT; US-PGPUB	2003/07/02 17:48
19	60	((901/47).CCLS.) and (registration or teach$3 or train$3 or learn$3) with (model or part or workpiece or work adj piece)	USPAT; US-PGPUB	2003/07/02 17:48